

Symmetrical solution for a reliability problem within the multi-optional uncertainty degree evaluation doctrine

The fifth part of the generalization for the degrading state maximal probability determination in the framework of the hybrid-optional functions entropy conditional optimality doctrine initiated in the preceding reports was presented in the given report. The issue will be continued with a following sequence of reports.

Introduction. Continuing the previous research dedicated to optimal periodicity of aeronautical engineering units' maintenance, it is an important issue to formulate the own concept (idea, problem, hypotheses), some original theoretical and practically applicable approaches [1-34].

State of the problem. In accordance with the graphs illustrated in Figure 1 [10, p. 37, Figure 3], one may state that the aircraft given functional system maintenance improvement, developed in someone's work [1-6], influences the corresponding values of the failure rates λ_{ij} and restoration rates μ_{ji} determining the process going on in the system.

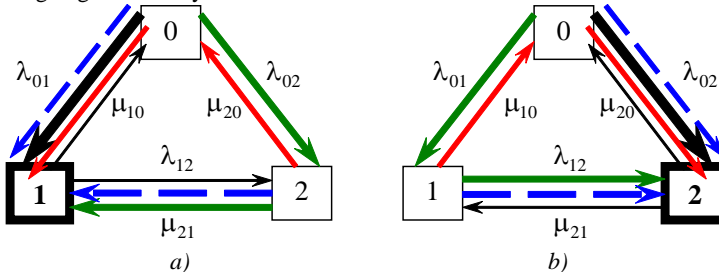


Fig. 1. Diagrammatic graphs of the three states of an aircraft functional system illustrating the prevailing flows with the maximum of the probability at the state of: a) – “1”; b) – “2”; [10, p. 37, Figure 3]

Here, in Figure 1 a), “0” designates the up state of the system; “1” – damage; “2” – failure. For the substantiated reasons, for the state of “2” to be a state without an “exit”, it has to be satisfied the conditions of $\mu_{20} = \mu_{21} = 0$. Then, it, the state of “2”, will be a real failure. In Figure 1 b), in an analogous manner “1” – failure; “2” – damage. And, it has to be $\mu_{10} = \lambda_{12} = 0$ in order the state of “1” should be a real failure.

Purpose of the paper. It is to prolong the proposed approach (doctrine) likewise in [8-16] considering the possibility of the situation depicted in Figure 1 b).

Problem setting. The problem might be, for instance, to choose an optimal maintenance periodicity for the improved aircraft given functional system. In its turn, it

might be done likewise in example described in the previous reports as well as in references [8-16]. The same approach as to the damage options effectiveness functions of $F_1^{(i)}$ is applicable for $F_2^{(i)}$ in the case when “1” – failure; “2” – damage (see Fig. 1 b)) with yielding the parallel to the Eq. (1), [8-10, p. 36, (63)], [11, p. 91, (16)]:

$$t_p^* = \frac{\ln(k_1\lambda_{01} + c_1) - \ln(k_2\lambda_{01} + c_1)}{k_2(\cdot) - k_1(\cdot)} \quad (1)$$

results, where t_p^* – optimal (delivering the sought maximal value to the probability) time of the maintenance periodicity;

$$k_{1,2} = \frac{-e_1 \pm \sqrt{e_1^2 - 4f_1g_1}}{2f_1}, \quad e_1 = \mu_{20} + \mu_{21} + \lambda_{12} + \mu_{10} + \lambda_{01} + \lambda_{02}, \quad (2)$$

$$f_1 = 1, \quad g_1 = b_1 + c_1 + d_1, \quad b_1 = \lambda_{12}\mu_{20} + \mu_{10}\mu_{20} + \mu_{10}\mu_{21}, \quad (3)$$

$$c_1 = \lambda_{01}\mu_{20} + \lambda_{01}\mu_{21} + \lambda_{02}\mu_{21}, \quad d_1 = \lambda_{01}\lambda_{12} + \lambda_{02}\lambda_{12} + \lambda_{02}\mu_{10}. \quad (4)$$

Now we ought to say that for the situation when the probability of state “2” $P_2(t)$ undergoes the extremum instead of the probability of state “1” $P_1(t)$ (see Fig. 1 b) and compare with Fig. 1 a)), the problem, **due to the symmetry**, has a symmetrical solution [8-10, p. 36, (64)], [11, p. 91, (17)]:

$$t_p^* = \frac{\ln(\lambda_{02}k_1 + d_1) - \ln(\lambda_{02}k_2 + d_1)}{k_2 - k_1}. \quad (5)$$

That is the system according to the developing stationary Poisson flow process has the possible states optimal options related with either the system of parameters $\{k_i, \lambda_{02}, d_1\}$ or $\{k_i, \lambda_{01}, c_1\}$ values for the initial moment probability of the state “0” being equaled to “1”.

These theoretical speculations and hypotheses can be represented with the diagrammatic graphs illustrating the flows shown in Figure 1.

In Figure 1 a), for instance, for the system of parameters of $\{k_i, \lambda_{01}, c_1\}$, as well as for the equation of M_{12} , which leads to the algebraic addition of the initial elementary intensities matrix \mathbf{M} , formed in the style likewise from the Erlang’s system [24], element of m_{12} , values; it is shown the prevailing flows that dominate the developing process [10, p. 37, (65)]:

$$M_{12} = p\lambda_{01} + c_1, \quad c_1 = \lambda_{01}\mu_{20} + \lambda_{01}\mu_{21} + \lambda_{02}\mu_{21}, \quad (6)$$

where p is the complex parameter (variable) of the Laplace transformation.

It is visible that intensities of λ_{12} and μ_{10} do not calibrate the optimal options’ dispositions. In that particular case, none of the flows from the state “1” is taken into account. The solutions in the view of either equation (1) or its symmetrical reflection solution as equation (5) are the general ones. That is, the partial cases are obtained from them.

Objective functional for procedures (1)-(6), like proposed in references [8-16], is as follows [8-10, p. 35, (55)], [11, p. 90, (11)] and expressed with formula (7):

$$\Phi_h = - \sum_{i=1}^3 [x F_1^{(i)}] \ln [x F_1^{(i)}] - \frac{t_p^*}{\lambda_{01}} \sum_{i=1}^3 [x F_1^{(i)}] (M_{12}^{(i)}) + \gamma \left[\sum_{i=1}^3 [x F_1^{(i)}] - 1 \right], \quad (7)$$

where x is an unknown parameter; $h_i = x F_1^{(i)}$ is the multi-optional hybrid functions depending upon the options effectiveness functions of $F_1^{(i)}$; t_p^*/λ_{01} is the intrinsic parameter of the system and the process, which is the ratio of the optimal (delivering the sought maximal value to the probability) time t_p^* of the maintenance periodicity, it is unknown yet for such problem formulation and the time of t_p^* is going to be determined as a solution, i.e. it is not the equation obtained on the basis of the absolutely probabilistic methods so far, however it will be, that is why the indication is the same, to the flow intensity λ_{01} ; $M_{12}^{(i)}$, is the algebraic addition of the initial elementary intensities matrix \mathbf{M} , formed in the style likewise from the Erlang's system [24], element of m_{12} ; γ is the parameter, coefficient, function (uncertain Lagrange multiplier, weight coefficient) for the normalizing condition.

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